

SH10shr Rotary Direct Drive Servo Valve

Product Overview

The SH10shr high speed servo valve is driven by a voice coil motor and enhances the magnetic field through double-layer magnetic array technology. Coils configured in series differentia are embedded in the double-layer magnetic field annulus. The spool of the servo valve is fixed to the end of the coil and can move freely within the valve sleeve. When current passes through the coil in the magnetic field, the coil will generate a strong thrust force to move the spool axially.

Key Features

- High-speed response: High-speed response refers to the dynamic characteristics of the valve, including step response and frequency
- Step response: 1.2 ms (0-100% command signal)
- Frequency response: Under ±24% command signal, the -3dB frequency can reach 750 Hz and -90° frequency can reach 540 Hz
- High safety: In case of emergency power failure, the spool will return to the predetermined position under the action of the spring
- High pollution resistance: Hydraulic cleanliness level NAS 1638 level 8 / ISO 4406-1999 19/16 can be used



SH10shr Technical Data

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General								
Design		Bi-directional Drive Servo Drive						
Actuation		Voice Coil Motor						
Size		DN10 / DN6						
Mounting Pattern		ISO 4401-05-05-0-05 / ISO 10372-04-04-0-92						
Ambient Temperature	°C (F)	-20+50 (-4+122) Integrated amplifier type -40+85 (-40+185) Separated amplifier type						
Mass	kg (lb)	6 (13.2)						
Vibration Resistance	g	10, 3 axes (Integrated amplifier type) 20, 3 axes (Separated amplifier type)						
Hydraulic Data								
Max Operating Pressure	bar (psi)	350 (5000) P, A, B, 70 (1000) T 350 (5000) P, A, B, 0.5 (7) Y						
Fluid		Hydraulic Oil DIN 51524, Part 1-3, other fluid on request						
Fluid Temperature	°C (F)	-20+80 (-4+176)						
Viscosity	cSt	Recommended: 15-500 Allowed: 5-400						
Rated Flow ⁽¹⁾	l/min US gal/min	10 – 80 2.6 – 21						
Leakage at 210 bar ⁽²⁾	l/min US gal/min	2% x Q _N						
Filtration		ISO 4406 (1999) 18/16/13						
Static/Dynamic Data								
Response Time at 100% Step Input ⁽³⁾	ms	<2						
Frequency Response (±25% signal) ⁽³⁾	Hz	750						
Hysteresis	%	<0.1						
Threshold	%	<0.3						
Null Shift ∆T=55 K	%	<1						
Electronics Data								
Supply Voltage	V	24 / 48						
Input Signal		±10V / ±10mA / 420mA						
Feedback Signal		±10V / ±10mA / 420mA						
EM Compatibility EN61000-6-2, EN55011: 1998+A1 1) Axis cut, measured with 70 bar pressure drop (two control edges)								

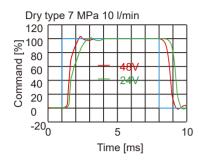
- Axis cut, measured with 70 bar pressure drop (two control edges)
- Axis cut valve
- Measured as 90% output rise time dP 70 bar P-T

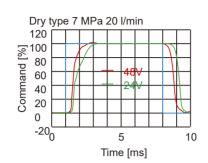
High Speed Servo Valve

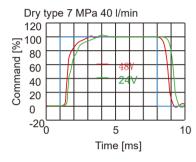


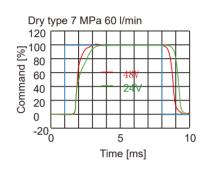
SH10shr Performance Graphs

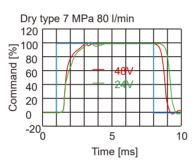
Step Response

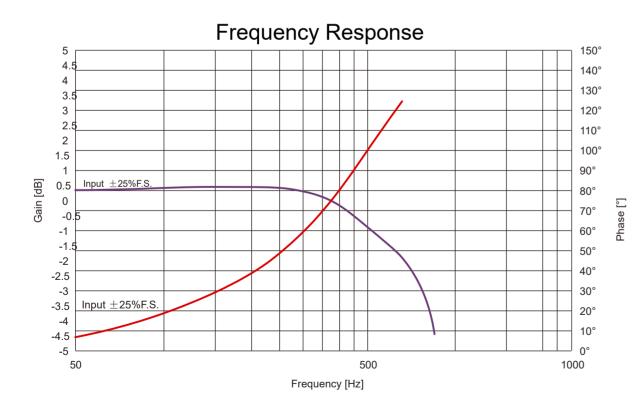








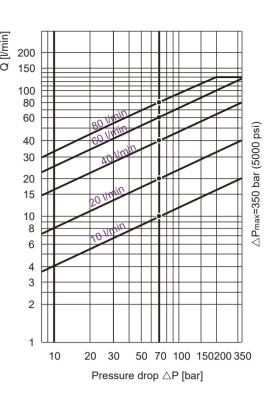




Test condition: $24V_{DC}$, $\Delta P=7MPa$, $Q_N=80$ I/min

Valve Load Flow Calculation

The actual flow is related to the displacement of the spool and the pressure drop across the two control edges of the valve port. At 100% demand signal input (e.g. +10V = valve port 100% opened), the flow rate at the rated pressure drop (ΔP_N =35 bar per control Edge) is defined as the rated flow $Q_{\mbox{\tiny N}}.$ For other values other than rated pressure drop, the flow rate of the valve is directly proportional to the square root of the pressure drop across the sharp edge orifices.



$$Q = Q_N \cdot \sqrt{\frac{\Delta P}{\Delta P_N}}$$

Q [l/min] - Actual Flow

Q_N [I/min] - Rated Flow

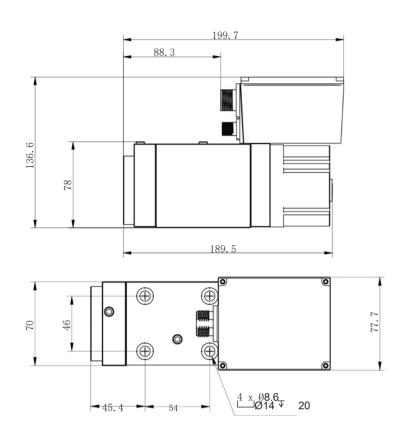
ΔP [bar] – Actual Pressure Drop across the Edge

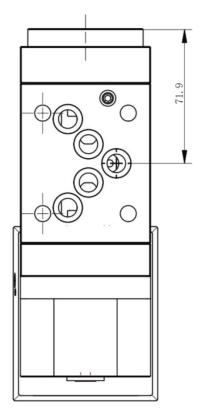
ΔP [bar] – Rated Pressure Drop across the Edge

The load flow rate Q of the valve can be calculated by this method when the average fluid velocity of the valve's P, A, B, T ports is less than 30 m/s.

High Speed Servo Valve High Speed Servo Valve

SH10shr Unit Dimensions





Dimensions are displayed in mm. Not to scale.

Mounting Surface Pattern

		Р	Α	В	T ₁	T ₂	Υ	F ₁	F ₂	F ₃	F ₄
Diameter Ø	mm	11	11	11	11	11	6.3	M6	M6	M6	M6
X Position	mm	27	16.7	37.3	3.2	50.8	62	0	62	62	0
Y Position	mm	6.2	21.4	21.4	32.4	32.4	11	0	46	46	46

The mounting manifold must confirm to ISO 4401-05-05-0-05.

Bolts (F_1, F_2, F_3, F_4)

Type: M6 x 65 DIN EN ISO 4762-10.9 Required Torque: 8.5 Nm

O-rings (P, A, B, T₁,T₂)

Type: 12.42 x 1.78, 5 x ISO 3601-1-014 Material: NBR, FKM

O-rings (Y)

Type: 5.28 x 1.78, 1 x ISO 3601-1-009

Material: NBR, FKM

